

Parallel Thinking

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We've sent a scouting robot into the wormhole to collect important data. You can move it up, down, left, and right from this control room, but if you try to move it through a wall, it will just stay in place. We need you to get the robot to several transmission points using as few moves as possible. There's just one problem: there are many parallel versions of the robot, each in slightly different dimensions. Your commands control all of them at once, and they must all be at their respective destinations simultaneously in order to transmit the data we need. Let us know as soon as you find where everything ends up.

KEY



Robot Deployment Point

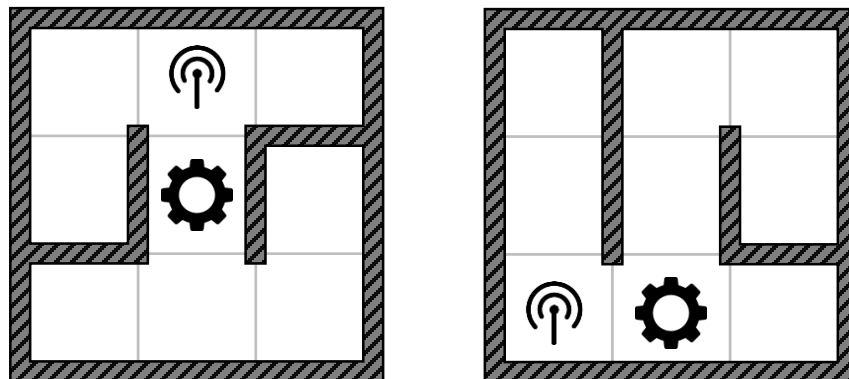


Transmission Point



Wall

EXAMPLE: Mission 0.0

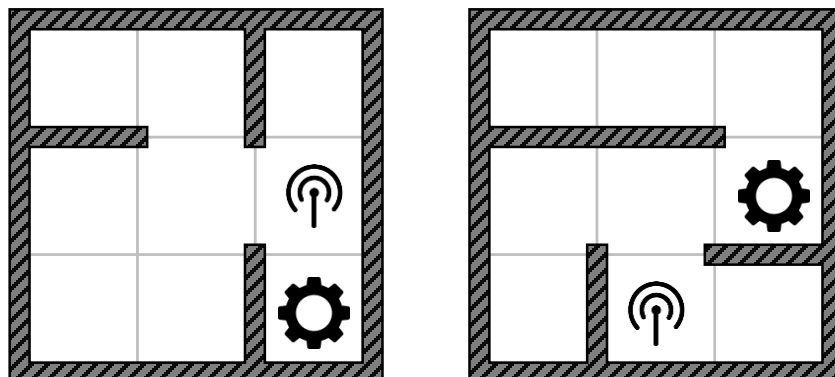


Moves:



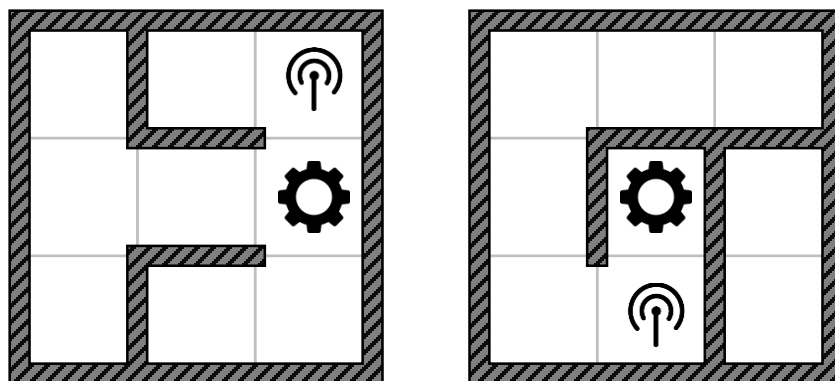


Mission 1.0



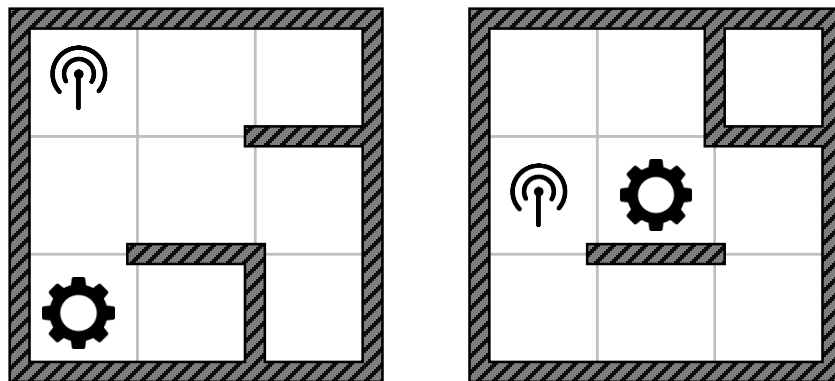
Moves:

Mission 2.0



Moves:

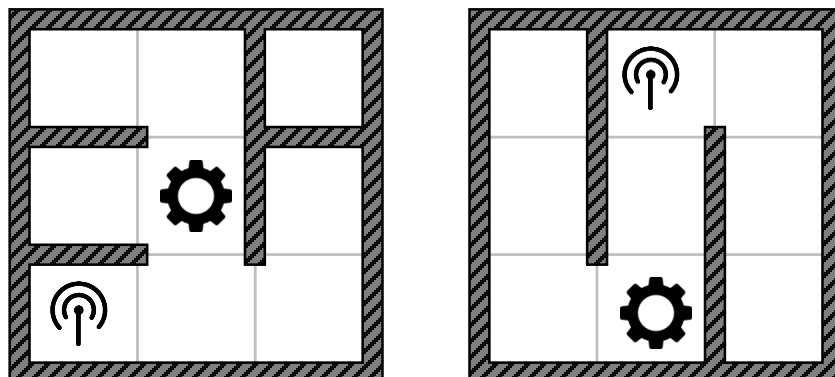
Mission 3.0



Moves:

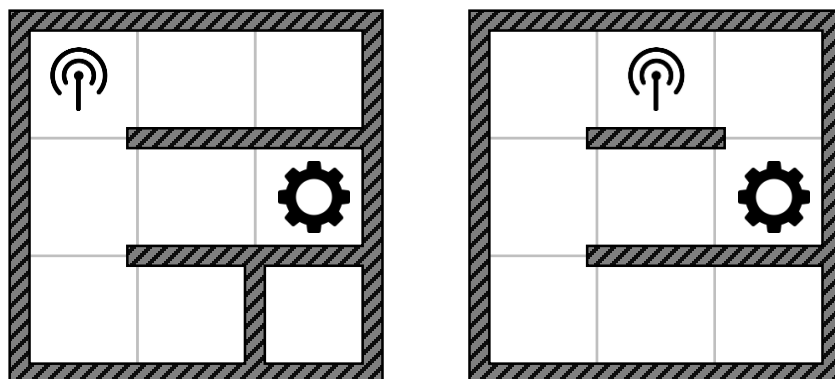


Mission 7.0



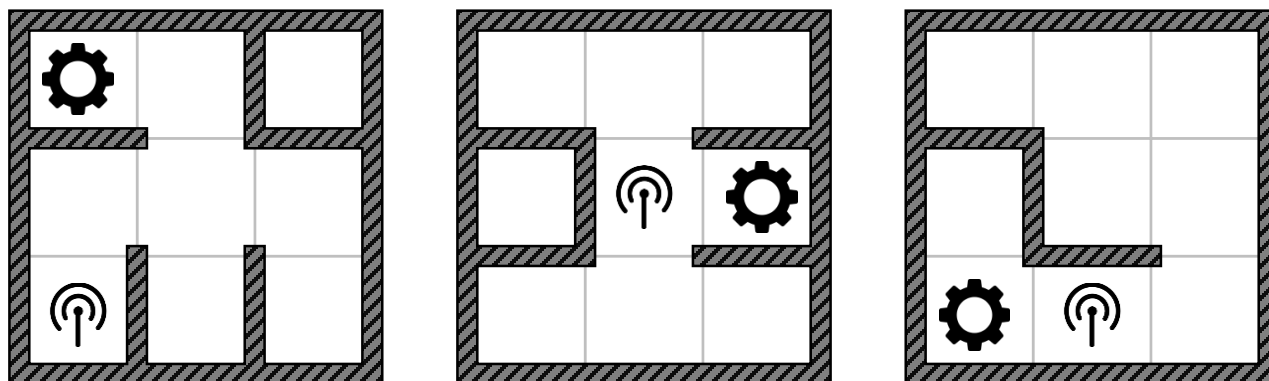
Moves:

Mission 8.0

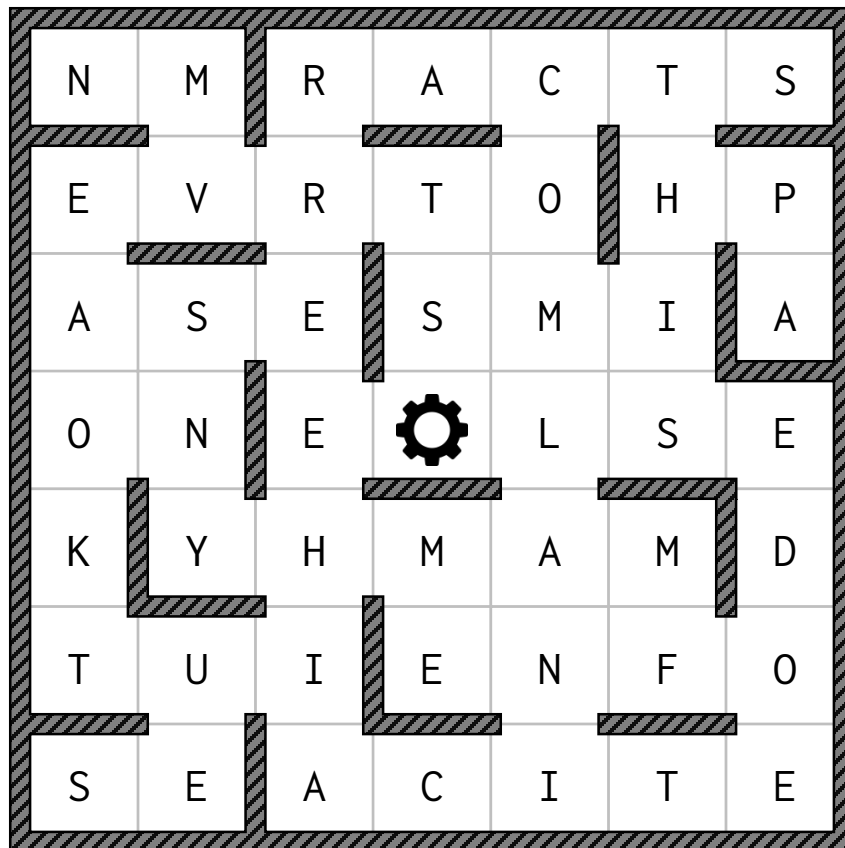


Moves:

Mission 9.0



Moves:



Robot resets position after each mission.